

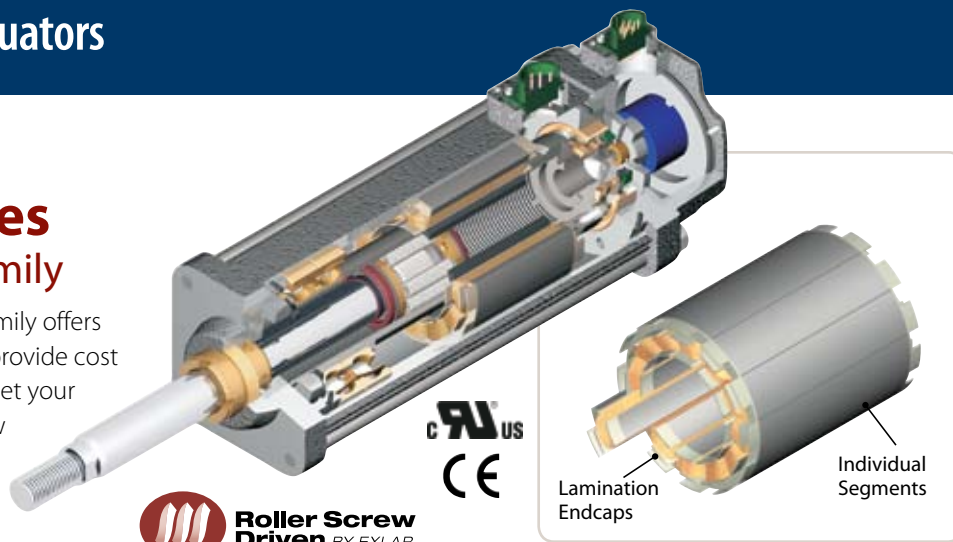
## Exlar GS Series Linear Actuator Family

The GS Series linear actuator family offers you two grades of actuator to provide cost effective options in order to meet your application's requirements. View the chart below to compare the GSX and GSM models.

All GS Series actuators use a specially designed roller screw mechanism for converting electric motor power into linear motion within the actuator. Planetary rollers assembled around the actuator's extending rod follow threads which are precisely machined on the inside surface of the actuator's hollow armature. Linear motion is produced in precise synchronization with the armature rotation. Because this roller screw mechanism has an inherently larger cumulative contact surface, these actuators have a much longer working life, and can handle heavier loads at higher speeds than is possible from a similarly sized unit built around a ball screw system.

Exlar's T-LAM segmented lamination stator technology delivers higher continuous motor torque than is available in traditionally wound motors. T-LAM technology consists of stator segments, each containing individual phase wiring for maximum motor performance. The improved efficiencies of the GSX Series are a result of the limited heat generation qualities inherent in the segmented stator design as seen above. The elimination of end turns in the stator, and use of thermally conductive potting removes the parts most susceptible to failure in a traditional stator. Other design advantages include:

- Neodymium-iron-boron magnets provide high flux density and maximum motor torque.
- Thermally conductive potting of the entire stator provides increased heat dissipation and provides protection from contamination in oil-cooled units.
- Each stator segment contains individual phase wiring. External winding of individual segments provides maximum slot fill for maximum motor performance.
- Motors with T-LAM technology have Class 180 H insulation systems compliant with UL requirements. UL recognized component.
- Motors with T-LAM technology are CE compliant



### The Actuator & Motor, All in one Compact Unit

With other actuator technologies, customers are usually responsible for engineering the completed linear motion system. This usually includes purchasing the motor, gear reducer, timing belt, mounting hardware, flexible couplings, etc. separately. Then they all must be assembled to perform properly in a given application.

GS Series actuators eliminate all this systems engineering. These units are single, fully integrated component packages – much smaller than traditional rotary-to-linear conversion mechanisms.

### Designed for Closed Loop Servo Systems

Their brushless servo design means GS Series units can be used in advanced closed-loop servo systems when velocity and positioning is required. Position feedback can be delivered in a number of different forms. These include resolvers, encoders or internally mounted linear position feedback sensors.

GSX and GSM Differences	GSX (pg 4)	GSM (pg 38)
Ingress Protection	IP65	IP54 (IP65 optional)
No. of Stacks	1, 2, 3	1, 2
Life BSY (Ball Screw Years)	15X	2 to 5X
Oil Cooling	Yes	No
Food Grade Paint	Yes	No
Electroless Nickel Housing	Yes	Yes
Stainless Steel Case	Yes	No
Hard Coat Anodized	Yes	Yes
LVDT FB	Yes (except 2" frame)	Yes (except 2" frame)
5.5 in. Frame	Yes	No
7 in. Frame	Yes	No
Force (lbf)	92 - 15,000	92 - 3,966
1.0 Lead	50 & 60 only	No
Rear Brake	all	all
Speeds (ips)	5 - 40	5 - 37.5
Electroless Nickel Connectors	Yes	Yes

## GSM Series Excellent Ball Screw Replacement

This design incorporates Exlar's patented roller screw technology with an integral brushless servo motor for medium to high performance motion control applications. The GSM Series offers 5 times the travel life of similarly sized ball screw actuators. It also provides a smaller package with higher speed and higher load capacity than ball screws and other traditional rotary to linear conversion mechanisms. These features make the GSM Series an excellent replacement for ball screw actuators.

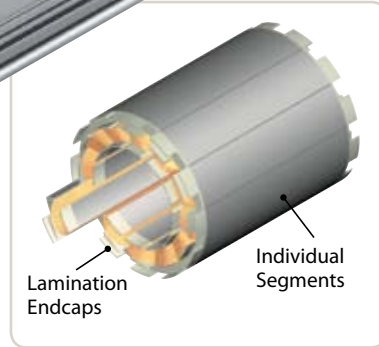
Selection of the proper feedback configuration allows GSM Series actuators to be powered by nearly every brand of brushless motor amplifier on the market. This flexibility allows GSM Series actuators to be incorporated into the highest performance single and multi-axis motion control systems in use today. In applications varying from food and beverage packaging, to multi-axis turning centers, to aircraft assembly, the GSM Series of actuators show incredible performance and durability.

Exlar's T-LAM technology incorporated into the motor design provides a solution with 35% more torque in the same package size as traditional brushless motors. The efficiencies of the GSM Series are a result of the limited heat generation qualities inherent in the segmented stator design. The elimination of end turns in the stator, and the use of thermally conductive potting removes the parts most susceptible to failure in a traditional stator. Other benefits include:

- Neodymium iron boron magnets provide high flux density and maximum motor torque.
- Thermally conductive potting of the entire stator provides increased heat dissipation and provides protection from contamination in oil-cooled units.
- Each stator segment contains individual phase wiring. External winding of individual segments provides maximum slot fill for maximum motor performance.
- Motors with T-LAM technology have Class H insulation systems compliant with UL requirements.



**Roller Screw  
Driven** BY EXLAR



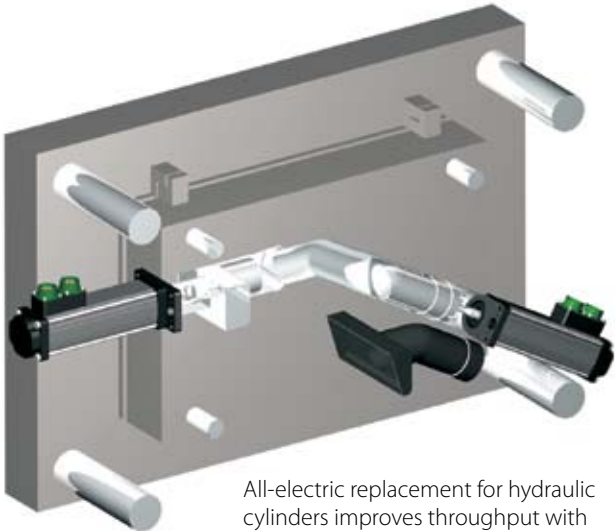
### Features/Characteristics

- T-LAM™ segmented lamination stator technology
- 2.25, 3.3 or 3.9 inch frame size
- 3, 5.9, 10, 12 and 18 inch strokes
- 0.1, 0.2, 0.4, 0.5 and .75 inch lead roller screws
- 7 to 75 lbf-in torque motor availability
- Up to 33 inch per second linear speeds
- 92 to 1983 lbf thrust capacity depending on motor selection
- Front flange, rear flange, rear clevis, trunnion, side, double side or extended tie rods mounting options
- Encoder feedback with MS style connectors
- Molded and shielded cables available
- Anodized aluminum housing
- Competitively priced with ball screw actuators
- 5 times the life of a similar sized ball screw actuator
- IP54 or IP65 sealing
- Class 180 H insulation
- UL recognized component

## Exlar GSM Series Linear Actuators Applications Include:

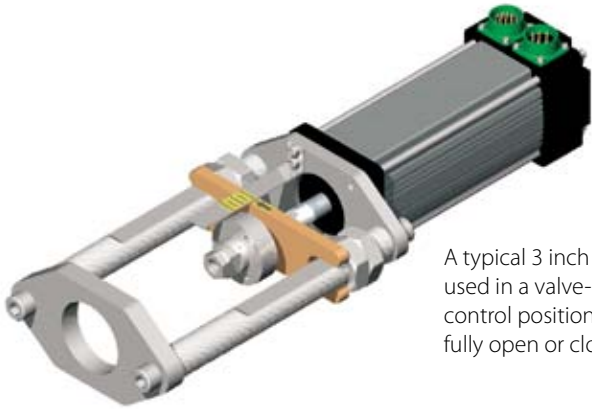
- |                                |                            |                                |                             |
|--------------------------------|----------------------------|--------------------------------|-----------------------------|
| Hydraulic cylinder replacement | Medical equipment          | Lifts                          | Ventilation control systems |
| Ball screw replacement         | Conveyor diverters / gates | Product sorting                | Pressing                    |
| Pneumatic cylinder replacement | Plastics equipment         | Material cutting               | Process control             |
| Chip and wafer handling        | Cut-offs                   | Material handling              | Tube bending                |
| Automated flexible fixturing   | Die cutters                | Riveting / fastening / joining | Welding                     |
| Dispensers                     | Packaging machinery        | Molding                        | Stamping                    |
| Machine tool                   | Entertainment              | Volumetric pumps               | Test stands                 |
| Automated assembly             | Sawmill equipment          | Semiconductor                  | Tension control             |
| Parts clamping                 | Open / close doors         | Pick and place systems         | Web guidance                |
| Automatic tool changers        | Fillers                    | Robot manipulator arms         | Wire winding                |
| Volumetric pumps               | Formers                    | Simulators                     | Food Processing             |
|                                | Precision grinders         | Precision valve control        |                             |
|                                | Indexing stages            |                                |                             |

GSM Series



All-electric replacement for hydraulic cylinders improves throughput with servo control and less maintenance for core-pull cylinders.

GSM-Series actuators can provide the precision at high force loads for fluid dispensing in a medical environment.



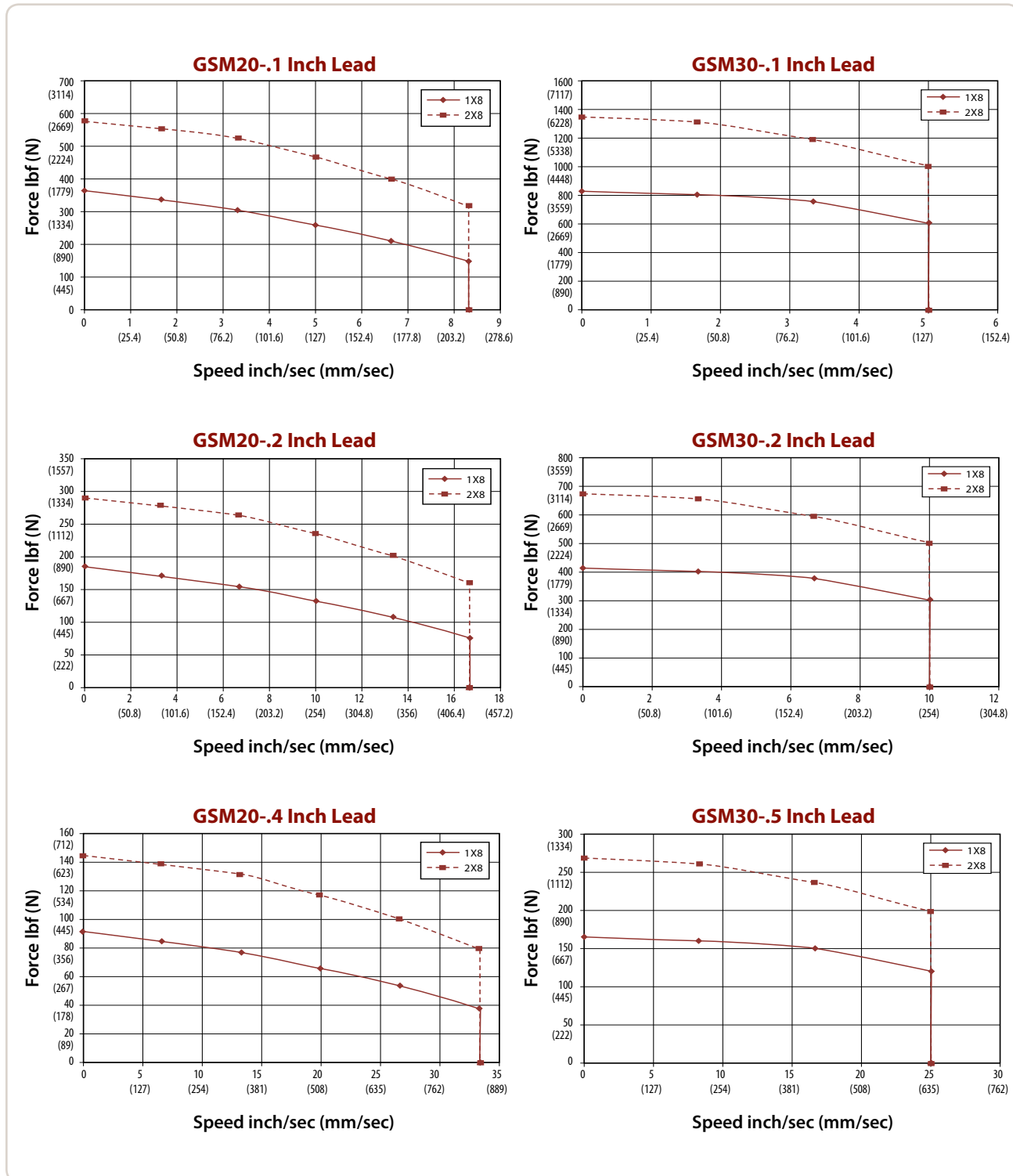
A typical 3 inch stroke GSM Series actuator used in a valve-modulating application can control position to +/- .5% while ready to fully open or close in less than 200 mSec.

# GSM Series Linear Actuators

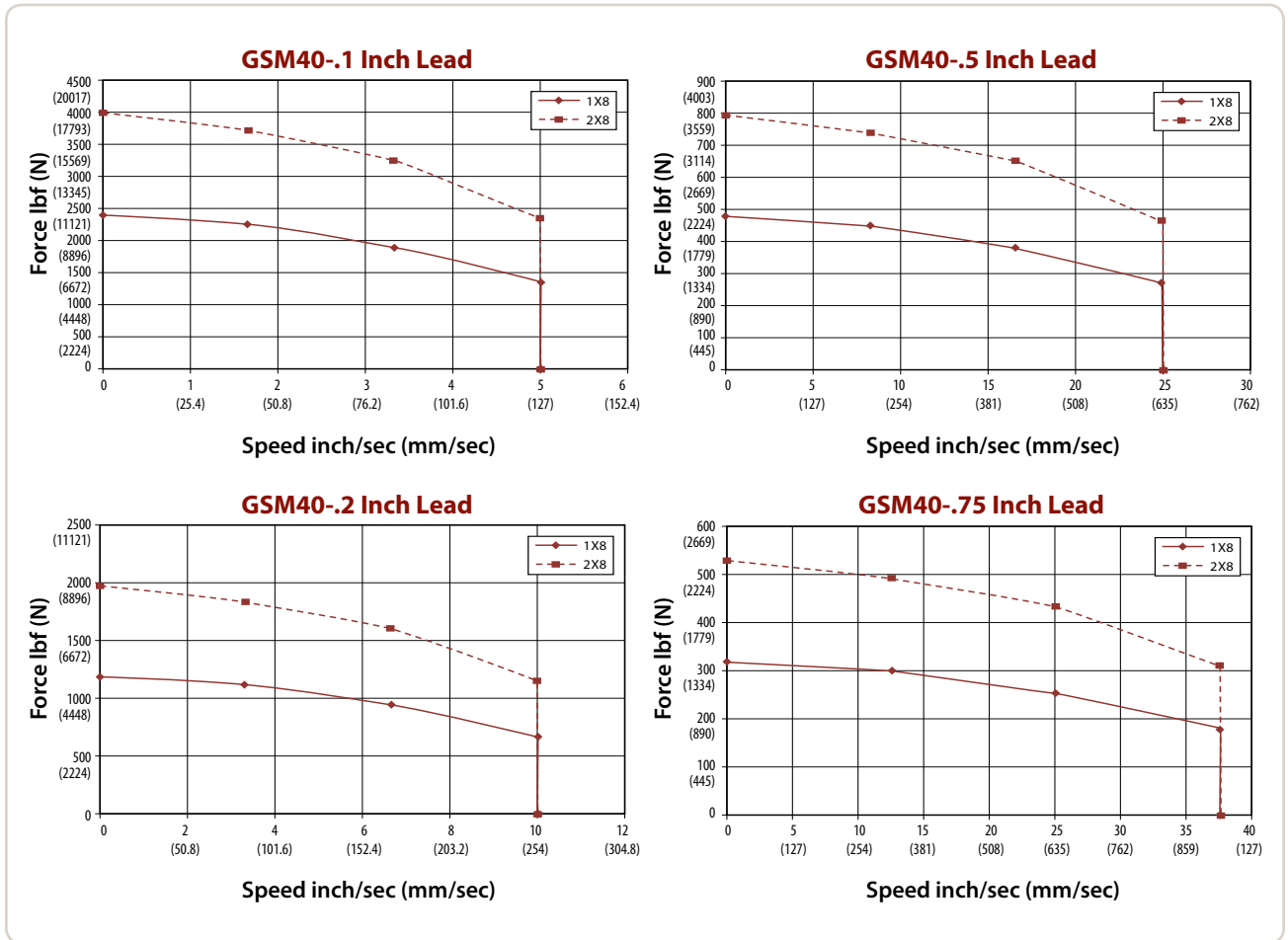
## GSM Series Performance

The below speed vs. force curves represent approximate continuous thrust ratings at indicated linear speed. Different types of servo amplifiers will offer varying motor

torque and thus actuator thrust. These values are at constant velocity and do not account for motor torque required for acceleration.



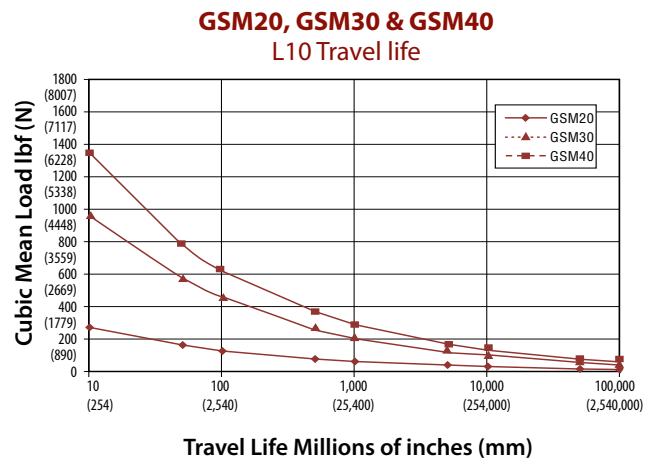
Test data derived using NEMA recommended aluminum heatsink 10" x 10" x 1/4" on GSM20 and 10" x 10" x 3/8" on GSM30



Test data derived using NEMA recommended aluminum heatsink 12" x 12" x 1/2" on GSM40

## Life Curves

The estimated travel life indicates the approximate expected travel life from the roller screw mechanism within the GSM30 at indicated cubic mean load. The chart below represents  $L_{10}$  travel life estimates. The reliability for these values is 90%. For higher than 90% reliability, the result should be multiplied by the following factors: 95% x 0.62; 96% x 0.53; 97% x 0.44; 98% x 0.33; 99% x 0.21. This information assumes that the roller screw is properly maintained and lubricated. The equation used to calculate the  $L_{10}$  life is:  $\text{Travel } (C/F)^3$  (lead) in millions of inches/mm. Where C = the dynamic load rating of the screw and F is the cubic mean load rating of the application. For higher than 90% reliability, derating of this value is implemented. Contact Exlar application engineering for details.



## GSM20 & GSM30 Performance Specifications

Model No.	Frame Size in (mm)	Stroke (nominal)* in (mm)	Screw Lead in (mm)	Continuous Force Rating	Max Velocity	Approx. Continuous Motor Torque	Maximum Static Load	Armature Inertia**	Dynamic Load Rating	Weight (approx.) lb (kg)
				lb (N) 1 stack/2 stack	in/sec (mm/sec)	1 stack/2 stack lb-in (N-m)				
GSM20-0301	2.25 (57)	3 (75)	0.1 (2.54)	367/578 (1632/2571)	8.33 (211.67)	7.3/11.5 (0.82/1.30)	750 (3336)	0.00101 (0.000114)	1568 (6970)	6.5 (2.9)
GSM20-0302			0.2 (5.08)	183/289 (814/1286)	16.77 (423.33)				1219 (5422)	
GSM20-0304			0.4 (10.16)	92/145 (409/645)	33.33 (846.67)				738 (3283)	
GSM20-0601	2.25 (57)	6 (150)	0.1 (2.54)	367/578 (1632/2571)	8.33 (211.67)	7.3/11.5 (0.82/1.30)	750 (3336)	0.00114 (0.000129)	1567 (6970)	7.0 (3.2)
GSM20-0602			0.2 (5.08)	183/289 (814/1286)	16.67 (423.33)				1219 (5422)	
GSM20-0604			0.4 (10.16)	92/145 (409/645)	33.33 (846.67)				738 (3283)	
GSM20-1001	2.25 (57)	10 (254)	0.1 (2.54)	367/578 (1632/2571)	8.33 (211.67)	7.3/11.5 (0.82/1.30)	750 (3336)	0.00133 (0.000150)	1567 (6970)	7.5 (3.4)
GSM20-1002			0.2 (5.08)	183/289 (814/1286)	16.67 (423.33)				1219 (5422)	
GSM20-1004			0.4 (10.16)	92/145 (409/645)	33.33 (846.67)				738 (3283)	
GSM20-1201	2.25 (57)	12 (300)	0.1 (2.54)	367/578 (1632/2571)	8.33 (211.67)	7.3/11.5 (0.82/1.30)	750 (3336)	0.00143 (0.000162)	1567 (6970)	8.0 (3.6)
GSM20-1202			0.2 (5.08)	183/289 (814/1286)	16.67 (423.33)				1219 (5422)	
GSM20-1204			0.4 (10.16)	92/145 (409/645)	33.33 (846.67)				738 (3283)	
GSM30-0301	3.3 (84)	3 (75)	0.1 (2.54)	829/1347 (3688/5992)	5 (127)	16.5/26.8 (1.86/3.03)	1620 (7206)	0.00319 (0.000360)	3310 (14724)	9.5 (4.3)
GSM30-0302			0.2 (5.08)	415/674 (1846/2998)	10 (254)				3570 (15880)	
GSM30-0305			0.5 (12.7)	166/269 (738/1197)	25 (635)				3016 (13416)	
GSM30-0601	3.3 (84)	5.9 (150)	0.1 (2.54)	829/1347 (3688/5992)	5 (127)	16.5/26.8 (1.86/3.03)	1620 (7206)	0.00361 (0.000408)	3310 (14724)	11.5 (5.2)
GSM30-0602			0.2 (5.08)	415/674 (1846/2998)	10 (254)				3570 (15880)	
GSM30-0605			0.5 (12.7)	166/269 (738/1197)	25 (635)				3016 (13416)	
GSM30-1001	3.3 (84)	10 (250)	0.1 (2.54)	829/1347 (3688/5992)	5 (127)	16.5/26.8 (1.86/3.03)	1620 (7206)	0.00416 (0.00047)	3310 (14724)	19 (8.6)
GSM30-1002			0.2 (5.08)	415/674 (1846/2998)	10 (254)				3570 (15880)	
GSM30-1005			0.5 (12.7)	166/269 (738/1197)	25 (635)				3016 (13416)	
GSM30-1201	3.3 (84)	12 (305)	0.1 (2.54)	829/1347 (3688/5992)	5 (127)	16.5/26.8 (1.86/3.03)	1620 (7206)	0.00443 (0.000501)	3310 (14724)	20.5 (9.3)
GSM30-1202			0.2 (5.08)	415/674 (1846/2998)	10 (254)				3570 (15880)	
GSM30-1205			0.5 (12.7)	166/269 (738/1197)	25 (635)				3016 (13416)	
GSM30-1401	3.3 (84)	14 (355)	0.1 (2.54)	829/1347 (3688/5992)	5 (127)	16.5/26.8 (1.86/3.03)	1620 (7206)	0.00473 (0.000534)	3310 (14724)	22 (10)
GSM30-1402			0.2 (5.08)	415/674 (1846/2998)	10 (254)				3570 (15880)	
GSM30-1405			0.5 (12.7)	166/269 (738/1197)	25 (635)				3016 (13416)	
GSM30-1801	3.3 (84)	18 (455)	0.1 (2.54)	829/1347 (3688/5992)	5 (127)	16.5/26.8 (1.86/3.03)	1620 (7206)	0.00533 (0.000602)	3310 (14724)	25 (11.3)
GSM30-1802			0.2 (5.08)	415/674 (1846/2998)	10 (254)				3570 (15880)	
GSM30-1805			0.5 (12.7)	166/269 (738/1197)	25 (635)				3016 (13416)	

\* Please note that stroke mm are nominal dimensions. \*\*Inertia +/- 5%

See page 43 for definition of terms.

## GSM40 Performance Specifications

Model No.	Frame Size in (mm)	Stroke (nominal)* in (mm)	Screw Lead in (mm)	Continuous Force Rating	Max Velocity in/sec (mm/sec)	Approx. Continuous Motor Torque	Maximum Static Load lb (N)	Armature Inertia** lb-in-s <sup>2</sup> (Kg-m <sup>2</sup> )	Dynamic Load Rating lb (N)	Weight (approx.) lb (kg)
				1 stack/2 stack lb (N)		1 stack/2 stack lb-in (N-m)				
GSM40-0601	3.9 (99)	6 (150)	0.1 (2.54)	2393/3966 (10645/17642)	5 (127)	47.6/78.9 (5.38/8.91)	3966 (17642)	0.0152 (0.001717)	4736 (21067)	20 (9.1)
GSM40-0602			0.2 (5.08)	1196/1983 (5320/8821)	10 (254)				4890 (21751)	
GSM40-0605			0.5 (12.7)	479/793 (2131/3527)	25 (635)				4218 (18763)	
GSM40-0608			0.75 (19.05)	319/529 (1419/2353)	37.5 (953)				3328 (14804)	
GSX40-0801	3.9 (99)	8 (200)	0.1 (2.54)	2393/3966/NA (10645/17642/NA)	5 (127)	47.6/78.9/NA (5.38/8.91/NA)	3966 (17642)	0.0163 (0.001842)	4736 (21067)	24 (10.9)
GSX40-0802			0.2 (5.08)	1196/1983/2692 (5320/8821/11975)	10 (254)	4890 (21751)				
GSX40-0805			0.5 (12.7)	479/793/1077 (2131/3527/4791)	25 (635)	4218 (18763)				
GSX40-0808			0.75 (19.05)	319/529/718 (1419/2353/3194)	37.5 (953)	3328 (14804)				
GSM40-1001	3.9 (99)	10 (250)	0.1 (2.54)	2393/3966 (10645/17642)	5 (127)	47.6/78.9 (5.38/8.91)	3966 (17642)	0.0175 (0.001977)	4736 (21067)	28 (12.7)
GSM40-1002			0.2 (5.08)	1196/1983 (5320/8821)	10 (254)				4890 (21751)	
GSM40-1005			0.5 (12.7)	479/793 (2131/3527)	25 (635)				4218 (18763)	
GSM40-1008			0.75 (19.05)	319/529 (1419/2353)	37.5 (953)				3328 (14804)	
GSM40-1201	3.9 (99)	12 (305)	0.1 (2.54)	2393/3966 (10645/17642)	5 (127)	47.6/78.9 (5.38/8.91)	3966 (17642)	0.0186 (0.002102)	4736 (21067)	32 (14.5)
GSM40-1202			0.2 (5.08)	1196/1983 (5320/8821)	10 (254)				4890 (21751)	
GSM40-1205			0.5 (12.7)	479/793 (2131/3527)	25 (635)				4218 (18763)	
GSM40-1208			0.75 (19.05)	319/529 (1419/2353)	37.5 (953)				3328 (14804)	
GSM40-1801	3.9 (99)	18 (455)	0.1 (2.54)	2393/3966 (10645/17642)	5 (127)	47.6/78.9 (5.38/8.91)	3966 (17642)	0.0220 (0.002486)	4736 (21067)	44 (19.9)
GSM40-1802			0.2 (5.08)	1196/1983 (5320/8821)	10 (254)				4890 (21751)	
GSM40-1805			0.5 (12.7)	479/793 (2131/3527)	25 (635)				4218 (18763)	

\* Please note that stroke mm are nominal dimensions. \*\*Inertia +/- 5%

See below for definition of terms.

### DEFINITION OF TERMS:

**Force Rating:** The linear force produced by the actuator at continuous motor torque.

**Max Velocity:** The linear velocity that the actuator will achieve at rated motor rpm.

**Continuous Motor Torque:** Torque produced by the motor at rated continuous current.

**Maximum Static Load:** The mechanical load limit of the actuator if re-circulated oil or other cooling method is used to allow higher than rated torque from the motor.

**Armature Inertia:** The rotary inertia of the armature of the GSM Series actuators. For calculation purposes, this value includes the screw inertia in a GSM actuator.

**Dynamic Load Rating:** A design constant used in calculating the estimated travel life of the roller screw. The cubic mean load is the load at which the device will perform one million revolutions.

## GSM20 Mechanical and Electrical Specifications

Nominal Backlash	in (mm)	0.008 (.20)							
Lead Accuracy	in/ft (mm/300 mm)	0.001 (.025)							
Maximum Radial Load	lb (N)	15 (67)							
Environmental Rating: Standard/Optional		IP54/IP65							
<b>Motor Stator</b>		<b>118</b>	<b>138</b>	<b>158</b>	<b>168</b>	<b>218</b>	<b>238</b>	<b>258</b>	<b>268</b>
<b>RMS SINUSOIDAL COMMUTATION</b>									
Continuous Motor Torque	lbf-in (Nm)	7.6 (0.86)	7.3 (0.83)	7.0 (0.79)	7.0 (0.79)	11.9 (1.35)	11.5 (1.30)	11.2 (1.27)	11.3 (1.28)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	2.5 (0.28)	5.2 (0.59)	8.3 (0.94)	9.5 (1.07)	2.5 (0.28)	5.2 (0.59)	8.9 (1.00)	10.2 (1.15)
Continuous Current Rating	Amps	3.4	1.6	0.9	0.8	5.4	2.5	1.4	1.2
Peak Current Rating	Amps	6.9	3.1	1.9	1.6	10.8	4.9	2.8	2.5
<b>TRAPEZOIDAL COMMUTATION</b>									
Continuous Motor Torque	lbf-in (Nm)	7.3 (0.82)	7.0 (0.79)	6.7 (0.76)	6.7 (0.76)	11.4 (1.29)	11.0 (1.24)	10.7 (1.21)	10.8 (1.22)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	1.9 (0.22)	4.1 (0.46)	6.5 (0.73)	7.4 (0.84)	1.9 (0.22)	4.1 (0.46)	6.9 (0.78)	7.9 (0.89)
Continuous Current Rating	Amps	4.2	1.9	1.1	1.0	6.6	3.0	1.7	1.5
Peak Current Rating	Amps	8.4	3.9	2.3	2.0	13.2	6.0	3.5	3.0
<b>MOTOR STATOR DATA</b>									
Voltage Constant (Ke) (+/- 10% @ 25°C)	Vrms/Krpm Vpk/Krpm	16.9 23.9	35.6 50.3	56.9 80.5	64.9 91.8	16.9 23.9	35.6 50.3	60.5 85.5	69.4 98.1
Pole Configuration		8	8	8	8	8	8	8	8
Resistance (L-L)(+/- 5% @ 25°C)	Ohms	2.6	12.5	35.2	45.8	1.1	5.3	16.0	20.7
Inductance (L-L)(+/- 15%)	mH	5.1	22.8	58.3	75.8	2.5	11.0	31.7	41.7
Brake Inertia	lbf-in-sec <sup>2</sup> (Kg-cm <sup>2</sup> )	0.00012 (0.135)							
Brake Current @ 24VDC	A	0.33							
Brake Holding Torque	lbf-in (Nm)	19 (2.2)							
Brake Engage/Disengage Time	ms	14/28							
Mechanical Time Constant (tm), ms	min	6.0	6.5	7.1	7.1	2.5	2.7	2.9	2.8
	max	8.5	9.2	10.1	10.1	3.6	3.9	4.0	4.0
Electrical Time Constant (te)	ms	2.0	1.8	1.7	1.7	2.2	2.1	2.0	2.0
Damping Constant	lbf-in/krpm (N-m/krpm)	0.55 (0.06)							
Friction Torque	lbf-in (Nm)	1.00 (0.11)							
Additional Friction Torque for Preloaded Screw	lbf-in (Nm)	1.25 (0.14)							
Bus Voltage	Vrms	115	230	400	460	115	230	400	460
Speed @ Bus Voltage	rpm	5000							
Insulation Class		180 (H)							

All ratings at 25 degrees Celsius  
 For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414.  
 Test data derived using NEMA recommended aluminum heatsink 10" x 10" x 1/4"

Specifications subject to change without notice.

## GSM30 Mechanical and Electrical Specifications

Nominal Backlash	in (mm)	0.008 (.20)							
Lead Accuracy	in/ft (mm/300 mm)	0.001 (.025)							
Maximum Radial Load	lb (N)	20 (90)							
Environmental Rating: Standard/Optional		IP54/IP65							
<b>Motor Stator</b>		<b>118</b>	<b>138</b>	<b>158</b>	<b>168</b>	<b>218</b>	<b>238</b>	<b>258</b>	<b>268</b>
<b>RMS SINUSOIDAL COMMUTATION</b>									
Continuous Motor Torque	lbf-in (Nm)	16.6 (1.88)	16.5 (1.87)	15.7 (1.77)	15.7 (1.78)	26.8 (3.03)	26.8 (3.03)	26.7 (3.02)	26.7 (3.01)
Torque Constant (Kt) (+/- 10% @ 25 °C)	lbf-in/A (Nm/A)	4.4 (0.49)	8.7 (0.99)	15.5 (1.75)	17.5 (1.98)	4.4 (0.49)	8.7 (0.99)	15.5 (1.75)	17.5 (1.98)
Continuous Current Rating	Amps	4.2	2.1	1.1	1.0	6.9	3.4	1.9	1.7
Peak Current Rating	Amps	8.5	4.2	2.3	2.0	13.7	6.8	3.8	3.4
<b>TRAPEZOIDAL COMMUTATION</b>									
Continuous Motor Torque	lbf-in (Nm)	15.9 (1.79)	15.8 (1.78)	14.9 (1.69)	15.0 (1.70)	25.6 (2.89)	25.6 (2.89)	25.5 (2.88)	25.5 (2.88)
Torque Constant (Kt) (+/- 10% @ 25 °C)	lbf-in/A (Nm/A)	3.4 (0.39)	6.8 (0.77)	12.1 (1.37)	13.6 (1.54)	3.4 (0.39)	6.8 (0.77)	12.1 (1.37)	13.6 (1.54)
Continuous Current Rating	Amps	5.2	2.6	1.4	1.2	8.4	4.2	2.4	2.1
Peak Current Rating	Amps	10.4	5.2	2.8	2.5	16.8	8.4	4.7	4.2
<b>MOTOR STATOR DATA</b>									
Voltage Constant (Ke) (+/- 10% @ 25 °C)	Vrms/Krpm (Vpk/Krpm)	29.9	59.7	106.0	119.5	29.9	59.7	106.0	119.5
Pole Configuration		8	8	8	8	8	8	8	8
Resistance (L-L) (+/- 5% @ 25 °C)	Ohms	2.8	11.2	39.5	49.6	1.1	4.5	14.1	18.0
Inductance (L-L) (+/- 15%)	mH	7.7	30.7	96.8	123.0	3.7	14.7	46.2	58.7
Brake Inertia	lbf-in-sec <sup>2</sup> (Kg-cm <sup>2</sup> )	0.00033 (0.38)							
Brake Current @ 24 VDC	A	0.5							
Brake Holding Torque	lbf-in (Nm)	70 (8)							
Brake Engage/Disengage Time	ms	19/29							
Mechanical Time Constant (tm), ms	min	6.5	6.5	7.3	7.2	2.6	2.6	2.6	2.6
	max	10.8	10.9	12.2	12.0	4.3	4.3	4.4	4.4
Electrical Time Constant (te)	ms	2.8	2.7	2.5	2.5	3.3	3.3	3.3	3.3
Damping Constant	lbf-in/krpm (N-m/krpm)	1.23 (0.14)							
Friction Torque	lbf-in (Nm)	2.00 (0.23)							
Additional Friction Torque for Preloaded Screw	lbf-in (Nm)	1.75 (0.20)							
Bus Voltage	Vrms	115	230	400	460	115	230	400	460
Speed @ Bus Voltage	rpm	3000							
Insulation Class		180 (H)							

All ratings at 25 degrees Celsius  
 For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414.  
 Test data derived using NEMA recommended aluminum heatsink 10" x 10" x 3/8"

Specifications subject to change without notice.

## GSM40 Mechanical and Electrical Specifications

Nominal Backlash	in (mm)	0.008 (.20)							
Lead Accuracy	in/ft (mm/300 mm)	0.001 (.025)							
Maximum Radial Load	lb (N)	30 (135)							
Environmental Rating: Standard/Optional		IP54/IP65							
<b>Motor Stator</b>		<b>118</b>	<b>138</b>	<b>158</b>	<b>168</b>	<b>218</b>	<b>238</b>	<b>258</b>	<b>268</b>
<b>RMS SINUSOIDAL COMMUTATION</b>									
Continuous Motor Torque	lbf-in (Nm)	47.6 (5.38)	47.6 (5.37)	44.7 (5.05)	45.5 (5.14)	78.9 (8.91)	78.9 (8.91)	78.8 (8.91)	79.7 (9.00)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/(Nm/A)	4.1 (0.46)	8.2 (0.93)	14.6 (1.65)	16.8 (1.90)	4.1 (0.46)	8.2 (0.93)	14.6 (1.65)	16.8 (1.90)
Continuous Current Rating	Amps	12.9	6.5	3.4	3.0	21.4	10.7	6.0	5.3
Peak Current Rating	Amps	25.9	12.9	6.9	6.0	42.9	21.4	12.1	10.6
<b>TRAPEZOIDAL COMMUTATION</b>									
Continuous Motor Torque	lbf-in (Nm)	45.5 (5.14)	45.4 (5.13)	42.7 (4.83)	43.5 (4.91)	75.3 (8.51)	75.3 (8.51)	75.3 (8.50)	76.1 (8.60)
Torque Constant (Kt) (+/- 10% @ 25°C)	lbf-in/A (Nm/A)	3.2 (0.36)	6.4 (0.72)	11.4 (1.28)	13.1 (1.48)	3.2 (0.36)	6.4 (0.72)	11.4 (1.28)	13.1 (1.48)
Continuous Current Rating	Amps	15.9	7.9	4.2	3.7	26.3	13.1	7.4	6.5
Peak Current Rating	Amps	31.7	15.8	8.4	7.4	52.5	26.3	14.8	13.0
<b>MOTOR STATOR DATA</b>									
Voltage Constant (Ke) (+/- 10% @ 25°C)	Vrms/Krpm Vpk/Krpm	28.1	56.1	99.5	114.8	28.1	56.1	99.5	114.8
Pole Configuration		8	8	8	8	8	8	8	8
Resistance (L-L)(+/- 5% @ 25°C)	Ohms	0.42	1.7	6.0	7.8	0.18	0.72	2.26	3.0
Inductance (L-L)(+/- 15%)	mH	3.0	11.9	37.5	49.8	1.4	5.8	18.2	24.2
Brake Inertia	lb-in-sec <sup>2</sup> (Kg-cm <sup>2</sup> )	0.00096 (1.08)							
Brake Current @ 24VDC	A	0.67							
Brake Holding Torque	lbf-in (Nm)	97 (11)							
Brake Engage/Disengage Time	ms	20/29							
Mechanical Time Constant (tm), ms	min	5.3	5.3	6.0	5.8	2.3	2.3	2.3	2.3
	max	7.7	7.7	8.7	8.4	3.3	3.3	3.3	3.2
Electrical Time Constant (te)	ms	7.0	7.0	6.2	6.4	8.0	8.0	8.0	8.2
Damping Constant	lbf-in/krpm (N-m/krpm)	3.25 (0.37)							
Friction Torque	lbf-in (Nm)	4.50 (0.51)							
Additional Friction Torque for Preloaded Screw	lbf-in (Nm)	3.00 (0.34)							
Bus Voltage	Vrms	115	230	400	460	115	230	400	460
Speed @ Bus Voltage	rpm	3000							
Insulation Class		180 (H)							

All ratings at 25 degrees Celsius  
 For amplifiers using peak sinusoidal ratings, multiply RMS sinusoidal Kt by .707 and current by 1.414.  
 Test data derived using NEMA recommended aluminum heatsink 12" x 12" x 1/2"

Specifications subject to change without notice.

## GSM Series Travel Options

### PF = Preloaded Follower

This option offers a true zero backlash follower for the GSM Series actuator. The dynamic load rating of zero backlash, preloaded screws is 63% of the dynamic load rating of the standard non-preloaded screws. The calculated travel life of a preloaded screw will be 25% of the calculated travel life of the same size and lead of a non-preloaded screw for the same application. Preloaded follower is not available with LT Linear feedback option.

### AR = External Anti-rotate Assembly

This option provides a rod and bushing to restrict the actuator rod from rotating when the load is not held by another method. Shorter actuators have single sided anti-rotation attachments. Longer lengths require attachments on both sides for proper operation. For AR dimensions, see page 22.

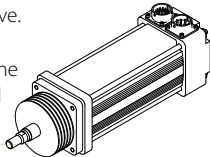
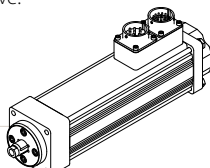
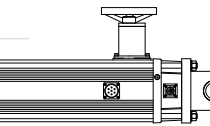
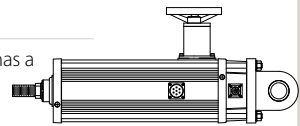
### RB = Rear Electric Brake

This option provides an internal holding brake for the GSM Series actuators. The brake is spring activated and electrically released.

### XT = Special Travel Option Selections

The XT Option can be used to specify various special travel options on the GSM Series of Linear Actuators. Because this option can be used to specify many things, it is important that an order including the -XT option spell out in detail, the exact options being selected by the including of the -XT in the model number.

It is recommended that prior to ordering an actuator including the -XT specifier that a quote be obtained through Exlar's special products application engineers for the desired options, and that quote be referenced on, or included with any order placed.

DESCRIPTIONS	
<b>Protective Bellows</b>	<p>This option provides an accordion style protective bellows to protect the main actuator rod from damage due to abrasives or other contaminants in the environment in which the actuator must survive. The standard material of this bellows is S2 Neoprene Coated Nylon, Sewn Construction. This standard bellows is rated for environmental temperatures of -40 to 250 degrees F. Longer strokes may require the main rod of the actuator to be extended beyond standard length. Not available with extended tie rod mounting option. Consult Exlar applications engineers for details.</p> 
<b>High Temp Protective Bellows</b>	<p>This option provides an accordion style protective bellows to protect the main actuator rod from damage due to abrasives or other contaminants in the environment in which the actuator must survive. The high temperature material of this bellows is D1 Teflon Coated Fiberglass, Sewn Construction. This standard bellows is rated for environmental temperatures of -67 to 500 degrees F. Longer strokes may require the main rod of the actuator to be extended beyond standard length. Not available with extended tie rod mounting option. Consult Exlar applications engineers for details.</p> 
<b>Splined Main Rod</b>	<p>This option provides a main rod manufactured of ball spline shafting, and the front seal and bushing assembly replaced with a ball spline nut to provide the anti-rotate function without using an external mechanism. Rod diameters are the closest metric equivalents to standard Exlar rod sizes. This option is <b>NOT</b> sealed in any way. This option is not suitable for any environment in which contaminants come in contact with the actuator, and may enter the actuator.</p> 
<b>Manual Drive Handwheel</b>	<p>This option provides for a manual drive handwheel on the side of the actuator. The handwheel has a engagement/disengagement lever which allows for disengagement of the handwheel during operation. This engagement/disengagement lever is not tied to the operation of the motor and requires that the user guarantee its disengagement before operating the motor. Not available on GSM20.</p> 

### L1, L2, L3 = Adjustable External Travel Switches

This option allows up to 3 external switches to be included with the GSM Series Actuator. These switches provide travel indication to the controller and are adjustable. See drawing on page 53. Must purchase external anti-rotate with this option.

### XL = Non-Standard Lubrication

This option provides for indication in the model number that the customer has specified a lubrication other than the standard provided by Exlar.

## Motor Speed Designators

All Exlar T-LAM™ motors and actuators carry a standard motor speed designator as defined below. This is representative of the standard base speed of the motor, for the selected bus voltage.

If the model number is created and the location for the motor speed designator is left blank, this is the base speed to which each motor will be manufactured. The model number can also be created including this standard speed designator.

Designator	Base Speed	Actuator/Motor Series
-50	5000 rpm	GSM20
-30	3000 rpm	GSM30, GSM40
01-99	Special Speed, Consult Exlar	

Exlar also provides the flexibility to manufacture all of its T-LAM products with special base speeds to match the customer's exact application requirements. This may be a higher than standard speed motor, or lower base speed than standard which will allow the customer to get the required torque, at a speed optimized to their application, and use the minimum amount of current from their amplifier.

The call out for a special speed is configured in the model number by using a two digit code from 01-99. These numbers represent the number, in hundreds, of RPM that will be the base speed for the particular motor.

For example, an GSM30-0301-MFM-EM2-138-30 motor that normally has a 3000 rpm standard winding, can be changed to a 3300 rpm winding by changing the -30, to a -33. It can be changed to a 5000 rpm winding by changing the -30 to a -50.

Changing this speed designator will change the ratings of the motor, and these must be obtained from Exlar applications engineers. Also, it is not possible to produce every possible speed from -01 to -99 for each motor at each voltage so please contact Exlar applications engineers for confirmation of the speed that is desired for the application.

## Feedback Options

### LT = ICT including signal conditioner

This option provides for an actuator containing an internally mounted ICT transducer spanning the full stroke of the actuator. Inquire with Exlar engineering for details and signal conditioner output preference. LT is not available with absolute feedback.

Due to the variability in size of some feedback devices, especially absolute feedback devices which are often very large relative to the size of the actuator motor, the actual size of the actuator may differ in length and width from these drawings for feedback types other than standard resolvers and standard encoders. Please consult Exlar for details. In the event that you order an actuator that differs from these standard dimensions, you will be sent a drawing of the final configuration of your actuator for approval.

## Motor Options

GSM motor options are described with a 3 digit code. The first digit calls out the stack length, the second the rated bus voltage, and the third the number of poles of the motor. Refer to the mechanical/electrical specifications for motor torque and actuator rated force.

<b>118 =</b>		115 Vrms		
<b>138 =</b>	1 stack	230 Vrms	8 Pole	Class 180 H
<b>158 =</b>		400 Vrms		
<b>168 =</b>		460 Vrms		
<b>218 =</b>	2 stack	115 Vrms	8 Pole	Class 180 H
<b>238 =</b>		230 Vrms		
<b>258 =</b>		400 Vrms		
<b>268 =</b>		460 Vrms		

Note: 3 stack not available in GSM Series

## Rod End Attachments

**Rear Clevis Pin Rod Eye**      **Spherical Rod Eye Rod Clevis**

See drawings on pages 52-53.

Attachments ordered separate from actuator.

## Housing Options

**P5 = IP65 Sealing Option**

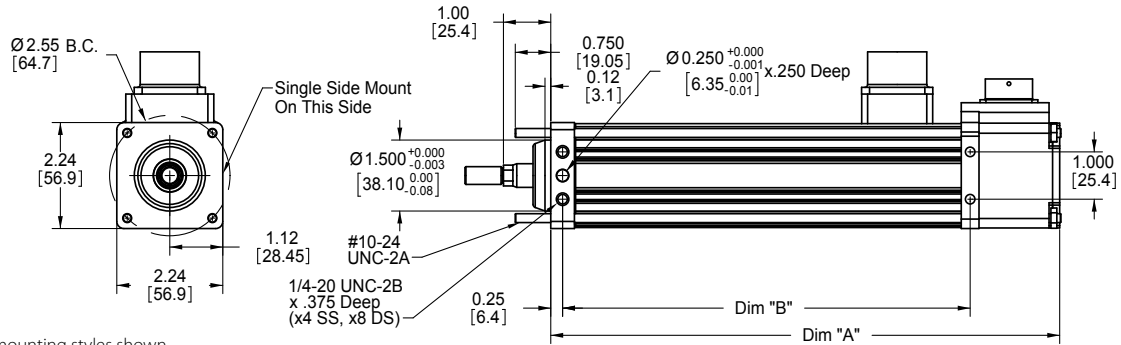
**HC = Type III Hard Coat Anodized, Class I**

This option provides an actuator with type III hard coat anodized coating. Class I, no dye.

**XH = Special Housing Option**

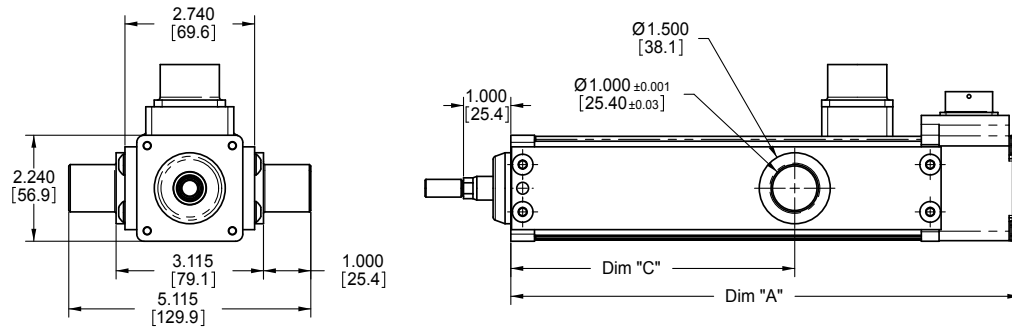
Any housing option that is not designated by the above codes should be listed as XH and described at time of order. All special options must be discussed with Exlar engineering.

## GSM20, Double Side Mounts or Extended Tie Rod Mount



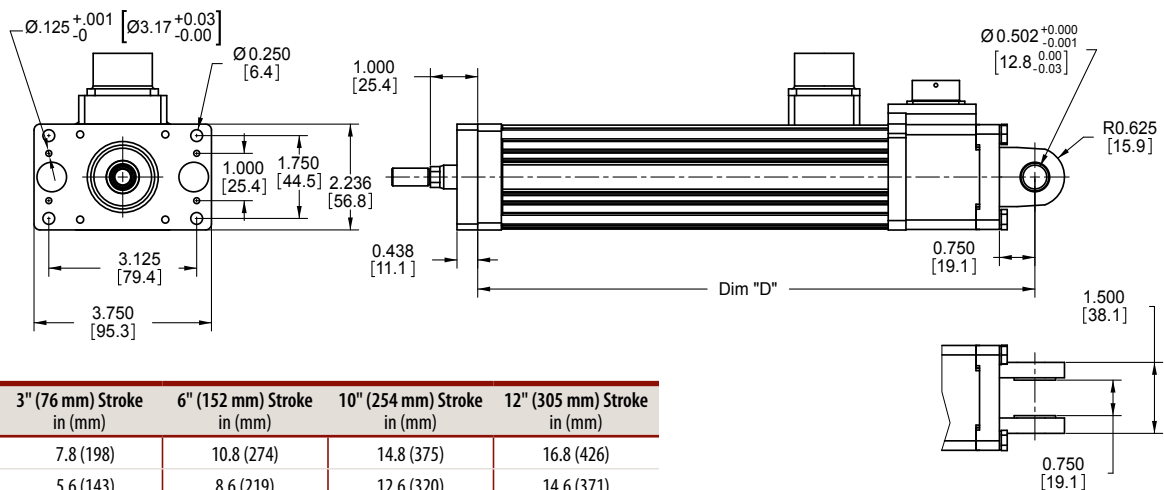
1. Three mounting styles shown
2. Shown view is standard side for single side mount
- \* If "M" metric tie rod option, thread = M5 x 0.8
- \* If "J" or "K" metric side mount options, M6 x 1.0 x 9 mm with Ø 6 mm M7 x 9 mm deep Dowel Hole

## GSM20 Side Trunnion Mount



- \* If "Q" metric side trunnion option, ø 25 mm h7

## GSM20 Rear Clevis Mount or Front Flange Mount



Dim	3" (76 mm) Stroke in (mm)	6" (152 mm) Stroke in (mm)	10" (254 mm) Stroke in (mm)	12" (305 mm) Stroke in (mm)
A	7.8 (198)	10.8 (274)	14.8 (375)	16.8 (426)
B	5.6 (143)	8.6 (219)	12.6 (320)	14.6 (371)
C	3.0 (76)	6.0 (152)	10.0 (254)	12.0 (305)
D	8.8 (223)	11.8 (299)	15.8 (401)	17.8 (452)

Note: Add 1.784 Inches to Dims "A & D" if ordering a Brake

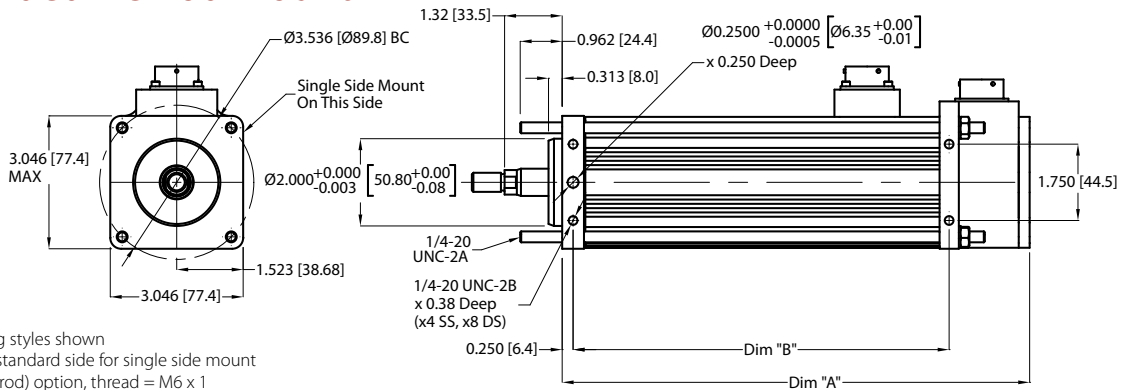
\* If "G" metric clevis option, ø12 mm +0.01 / -0.06

Drawings subject to change.  
Consult Exlar for certified drawings.

Due to the size of many absolute encoders, the selection of such feedback types for the size 20 and 30 actuators results in a larger package size than is shown in the drawings. Consult Exlar for details, or refer to the drawings provided after receipt of order.

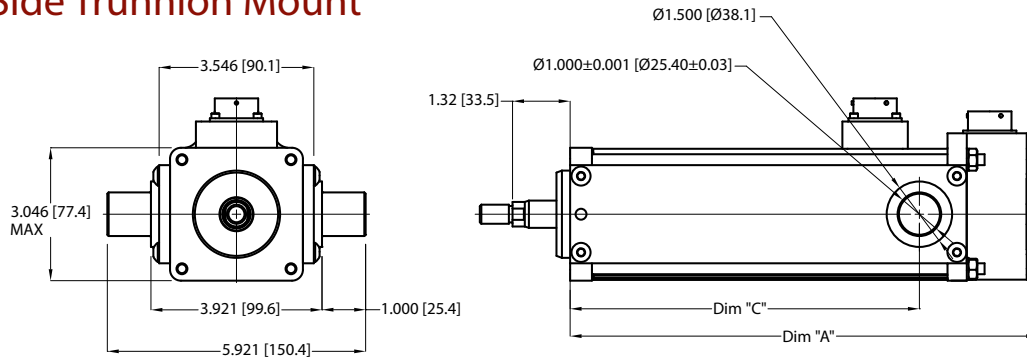
1. Two mounting styles shown
2. With flange mount, dimension A is equivalent to the top two drawing views.

## GSM30, Double Side Mounts or Extended Tie Rod Mount



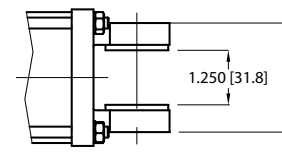
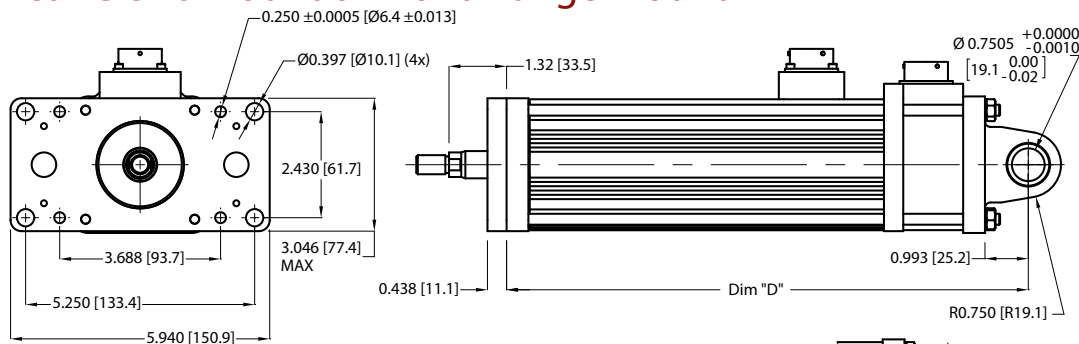
1. Three mounting styles shown
  2. Shown view is standard side for single side mount
- \* If "M" (metric tie rod) option, thread = M6 x 1  
 \* If "J" or "K" metric side mount options, M6 x 1.0 x 9 mm deep with Ø 6 mm M7 x 9 mm deep dowel hole

## GSM30 Side Trunnion Mount



\*If "Q" metric side trunnion option, Ø 25 mm h7

## GSM30 Rear Clevis Mount or Front Flange Mount



Dim	3" (76 mm) Stroke in (mm)	6" (152 mm) Stroke in (mm)	10" (254 mm) Stroke in (mm)	12" (305 mm) Stroke in (mm)	14" (355 mm) Stroke in (mm)	18" (457 mm) Stroke in (mm)
A	8.2 (209)	10.7 (272)	15.2 (387)	17.2 (437)	19.2 (539)	23.2 (590)
B	6.1 (156)	8.6 (219)	13.1 (333)	15.1 (384)	17.1 (485)	21.1 (536)
C	5.4 (137)	8.0 (203)	10.0 (254)	12.0 (305)	14.0 (406)	18.0 (457)
D	9.5 (241)	12.0 (304)	16.5 (418)	18.5 (469)	20.5 (570)	24.5 (621)

Note: Add 1.6 Inches to Dims "A" & "D" if ordering a Brake.

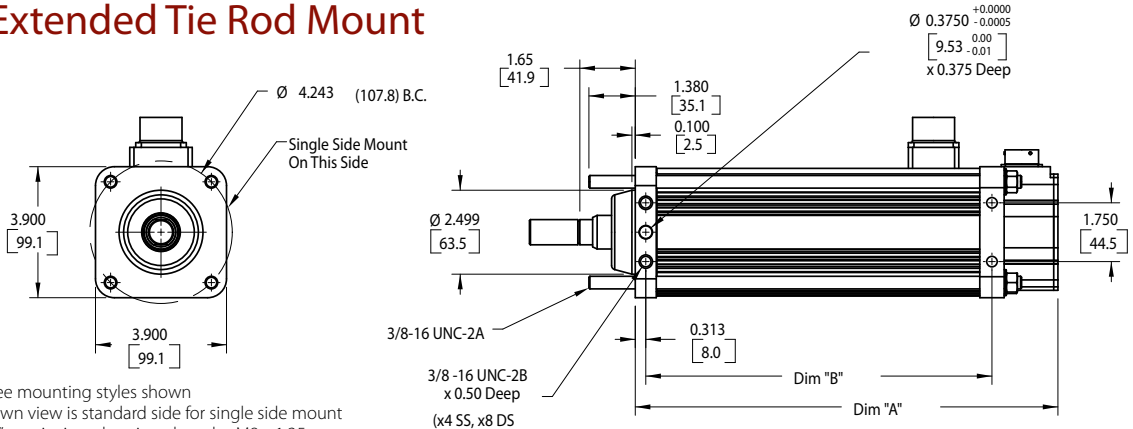
\* If "G" metric clevis option, Ø20 mm +0.01 / -0.07

Drawings subject to change.

Consult Exlar for certified drawings.

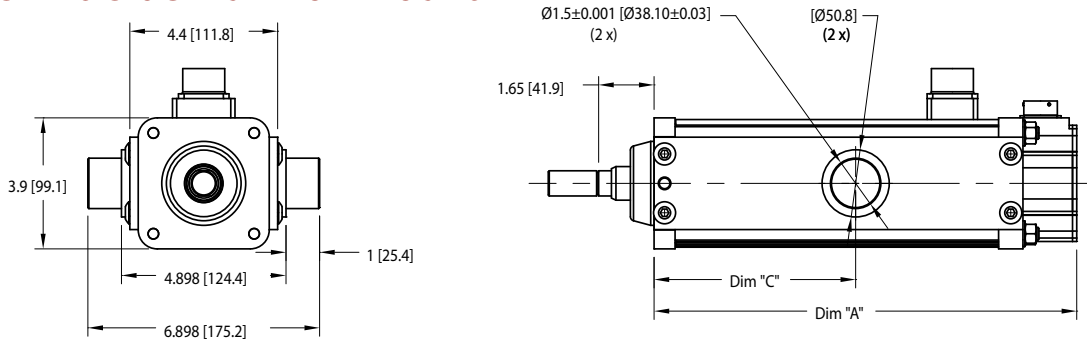
1. Two mounting styles shown
2. With flange mount, dimension A is equivalent to the top two drawings

## GSM40, Double Side Mounts or Extended Tie Rod Mount



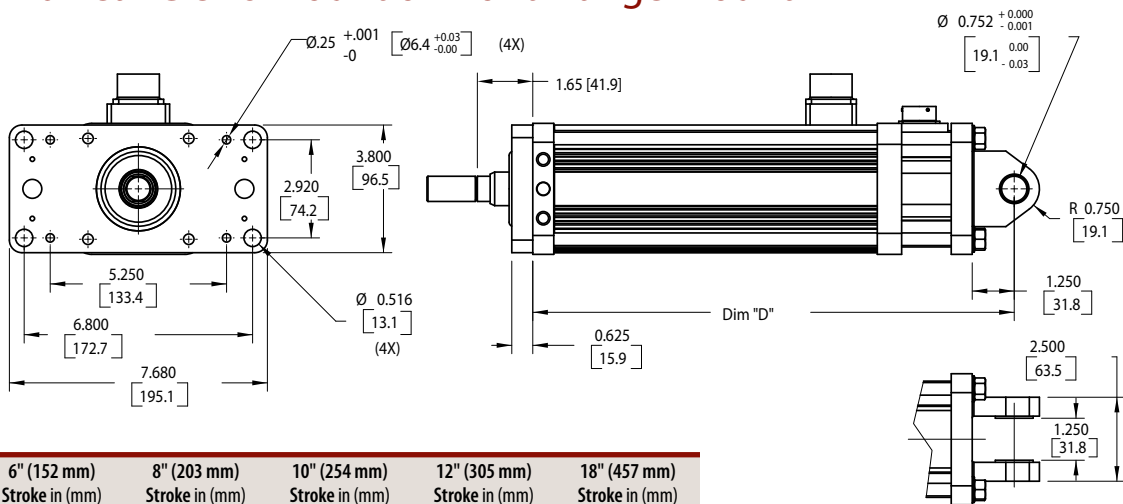
1. Three mounting styles shown
2. Shown view is standard side for single side mount
- \* If "M" metric tie rod option, thread = M8 x 1.25
- \* If "J" or "K" metric side mount options, M10 x 1.5 x 19 mm deep with Ø 8 mm M7 x 12 mm deep dowel hole

## GSM40 Side Trunnion Mount



\* If "Q" metric side trunnion option, Ø 35 mm h7

## GSM40 Rear Clevis Mount or Front Flange Mount



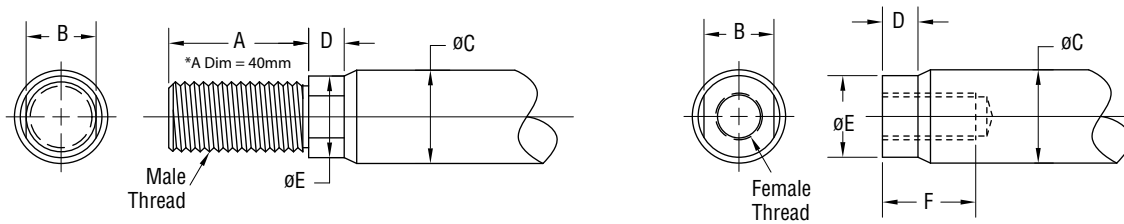
Dim	6" (152 mm) Stroke in (mm)	8" (203 mm) Stroke in (mm)	10" (254 mm) Stroke in (mm)	12" (305 mm) Stroke in (mm)	18" (457 mm) Stroke in (mm)
A	12.6 (320)	14.6 (370)	16.6 (421)	18.6 (472)	24.6 (624)
B	10.3 (262)	12.3 (313)	14.3 (364)	16.3 (414)	22.3 (567)
C	6.0 (152)	8.0 (203)	10.0 (254)	12.0 (305)	18.0 (457)
D	14.3 (364)	16.3 (415)	18.3 (466)	20.3 (516)	26.3 (669)

Note: Add 2.33 Inches to Dims "A & D" if ordering a Brake (p. 30).

\* If "G" metric clevis option, ø20 mm +0.01 / -0.07

. Two mounting styles shown  
. With flange mount, dimension A is equivalent to top two drawings

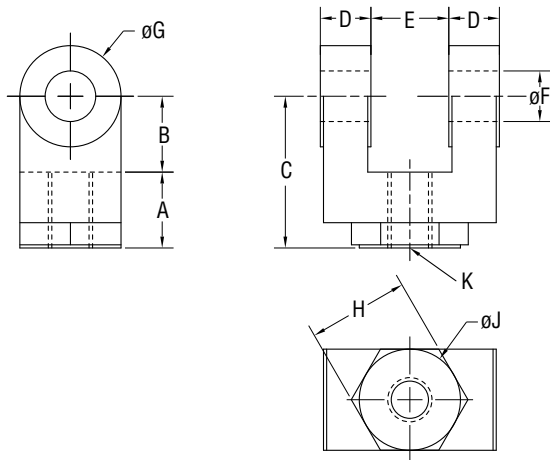
## Actuator Rod End Options



	A	B	ØC	D	ØE	F	Male U.S.	Male Metric	Female U.S.	Female Metric
<b>GSM20</b> in (mm)	0.813 (20.7)	0.375 (9.5)	0.500 (12.7)	0.200 (5.1)	0.440 (11.2)	0.750 (19.1)	3/8 – 24 UNF – 2A	M8 x 1.6g	5/16 – 24 UNF – 2B	M8 x 1.6h
<b>GSM30</b> in (mm)	0.750 (19.1)	0.500 (12.7)	0.625 (15.9)	0.281 (7.1)	0.562 (14.3)	0.750 (19.1)	7/16 – 20 UNF – 2A	M12 x 1.75* 6g	7/16 – 20 UNF – 2B	M10 x 1.5 6h
<b>GSM40</b> in (mm)	1.500 (38.1)	0.750 (19.1)	1.000 (25.4)	0.381 (9.7)	0.875 (22.2)	1.000 (25.4)	3/4 – 16 UNF – 2A	M16 x 1.5 6g	5/8 – 18 UNF – 2B	M16 x 1.5 6h

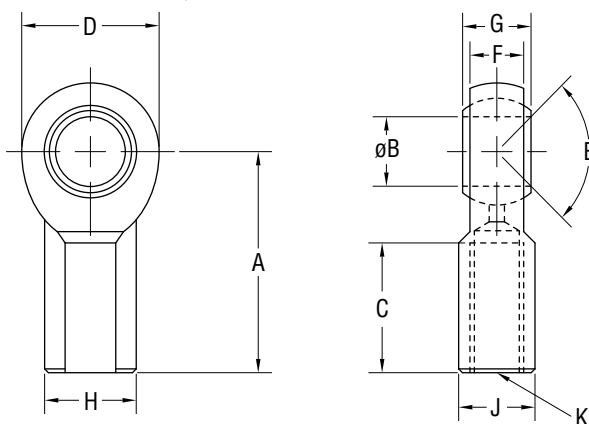
Part numbers for rod attachment options indicate the through hole size or pin diameter. Before selecting a spherical rod eye for use with a GSM series actuator, please consult the information on the anti-rotation option for the GSM actuators. Spherical rod eyes will allow the rod to rotate if the load is not held.

## Rod Clevis Dimensions



in (mm)	GSM20 RC038	GSM30 RC050	GSM40 RC075
<b>A</b>	0.787 (20)	0.75 (19.1)	1.125 (28.58)
<b>B</b>	0.787 (20)	0.75 (19.1)	1.25 (31.75)
<b>C</b>	1.574 (40)	1.50 (38.1)	2.375 (60.3)
<b>D</b>	0.287 (7.3)	0.50 (12.7)	0.625 (15.88)
<b>E</b>	0.375 (9.5)	0.765 (19.43)	1.265 (32.13)
<b>ØF</b>	0.375 (9.5)	0.50 (12.7)	0.75 (19.1)
<b>ØG</b>	0.75 (19.1)	1.00 (25.4)	1.50 (38.1)
<b>H</b>	NA	1.00 (25.4)	1.25 (31.75)
<b>ØJ</b>	NA	1.00 (25.4)	1.25 (31.75)
<b>K</b>	3/8-24	7/16-20	3/4-16

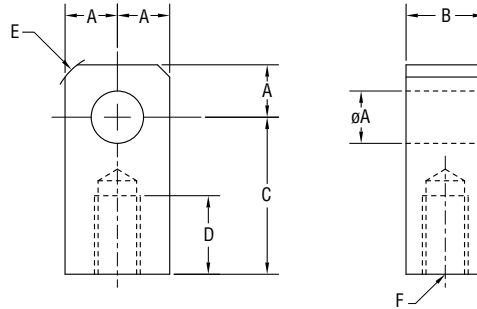
## Spherical Rod Eye Dimensions



in (mm)	GSM20 SRM038	GSM30 SRM044	GSM40 SRM075
<b>A</b>	1.625 (41.3)	1.81 (46.0)	2.88 (73.2)
<b>ØB</b>	.375 (9.525)	0.438 (11.13)	0.75 (19.1)
<b>C</b>	.906 (23.0)	1.06 (26.9)	1.72 (43.7)
<b>D</b>	1.0 (25.4)	1.13 (28.7)	1.75 (44.5)
<b>E</b>	6 deg	14 deg	14 deg
<b>F</b>	.406 (10.3)	0.44 (11.1)	0.69 (17.5)
<b>G</b>	.500 (12.7)	0.56 (14.2)	0.88 (22.3)
<b>H</b>	.688 (17.4)	0.75 (19.1)	1.13 (28.7)
<b>J</b>	.562 (14.3)	0.63 (16.0)	1.00 (25.4)
<b>K</b>	3/8-24	7/16-20	3/4-1

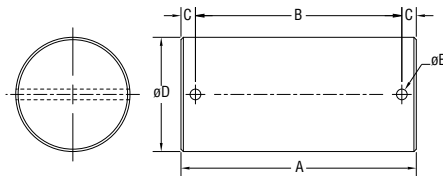
Drawings subject to change. Consult Exlar for certified drawings.

## Rod Eye Dimensions



in (mm)	GSM20 RE038	GSM30 RE050	GSM40 RE075
ØA	0.50 (12.7)	0.50 (12.7)	0.75 (19.1)
B	0.560 (14.2)	0.75 (19.1)	1.25 (31.8)
C	1.00 (25.4)	1.50 (38.1)	2.06 (52.3)
D	0.50 (12.7)	0.75 (19.1)	1.13 (28.7)
E	0.25 x 45°	0.63 (16.0)	0.88 (22.3)
F	3/8 - 24	7/16 - 20	3/4 - 16

## Rod Clevis Pin Dimensions



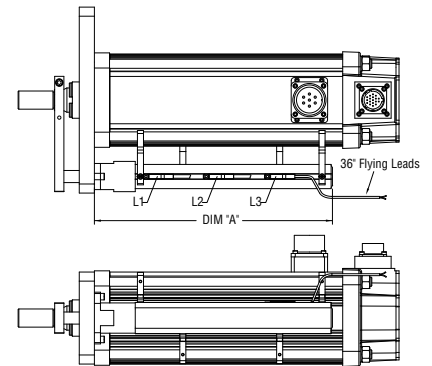
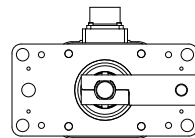
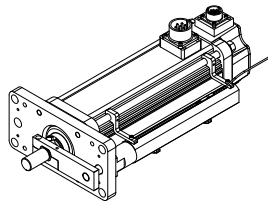
in (mm)	A	B	C	ØD	ØE
CP050 <sup>1</sup>	2.28 (57.9)	1.94 (49.28)	0.17 (4.32)	0.50" +0.000/-0.002 (12.7 mm +0.00/-0.05)	0.106 (2.69)
CP075 <sup>2</sup>	3.09 (78.5)	2.72 (69.1)	0.19 (4.82)	0.75" +0.000/-0.002 (19.1 mm +0.00/-0.05)	0.14 (3.56)

<sup>1</sup> Fits GSM30 rear clevis, RC050 and RE050

<sup>2</sup> Fits GSM30, 40 and RC075, RE075 and SRM075

## GSM20, GSM30 and GSM40 External Limit Switch Extension Options

Dim A	3" (76 mm) stroke in (mm)	6" (152 mm) stroke in (mm)	8" (203 mm) stroke in (mm)	10" (254 mm) stroke in (mm)	12" (305 mm) stroke in (mm)	18" (457 mm) stroke in (mm)
GSM20	5.515 (140.1)	8.515 (216.3)	NA	12.5 (317.5)	14.515 (368.7)	NA
GSM30	6.932 (176.1)	9.832 (249.7)	NA	13.832 (351.3)	15.832 (402.1)	21.832 (554.5)
GSM40	NA	9.832 (249.7)	11.83 (300.5)	13.832 (351.3)	15.832 (402.1)	21.832 (554.5)



\* Dimensions for Anti rotate option can be seen on page 22.

The external limit switch option (requires anti-rotate option) for the GSM Series of linear actuators provides the user with 1, 2 or 3 externally mounted adjustable switches for use as the end of travel limit switches or home position sensors.

The number of switches desired is selected by ordering the L1, L2 or L3 option, in which 1, 2 or 3 switches will be provided, respectively.

The switches are 9-30 VDC powered, PNP output, with either normally open or normally closed logic operation depending on the switch configuration ordered. Below is a diagram which logic operation will be provided for each switch, based on the option ordered.

Option	SW1	SW2	SW3
L1	Not Supplied	Normally Open	Not Supplied
L2	Normally Closed	Not Supplied	Normally Closed
L3	Normally Closed	Normally Open	Normally Closed

Switch Type	Exlar Part Number	Turck Part Number
Normally Closed Switch	43404	BIM-UNT-RP6X
Normally Open Switch	43403	BIM-UNT-AP6X

Drawings subject to change. Consult Exlar for certified drawings.

**AA = GSM Actuator Size (nominal)**

- 20 = 2 in (60 mm) frame
- 30 = 3 in (80 mm) frame
- 40 = 4 in (100 mm) frame

**BB = Stroke Length**

- 03 = 3 in (75 mm) GSM20 and GSM30
- 06 = 6 in (150 mm) all GSM30 = 5.9 in (150 mm)
- 08 = 8 in (200 mm) GSM40
- 10 = 10 in (250 mm) GSM20, GSM30 and GSM40
- 12 = 12 in (300 mm) GSM20, GSM30 and GSM40
- 14 = 14 in (355 mm) GSM30
- 18 = 18 in (450 mm) GSM30 and GSM40

**CC = Lead**

- 01 = 0.1 inch (all models)
- 02 = 0.2 inch (all models)
- 04 = 0.4 inch (GSM20)
- 05 = 0.5 inch (GSM30 and GSM40)
- 08 = 0.75 inch (GSM40)<sup>3</sup>

**D = Connections**

- M = Manufacturer's connector<sup>1</sup>
- I = Exlar standard M23 style
- A = MS style (anodized)
- D = MS style (electroless nickel)
- B = Embedded leads 3 ft. std.
- P = Embedded leads w/plug 3 ft. standard w/"A" plug
- J = Embedded leads w/"I" plug, 3 ft. std
- X = Special (please specify)

**E = Mounting**

- B = Front and rear flange
- C = Rear clevis
- F = Front flange
- R = Rear flange
- S = Side mount
- D = Double side mount
- T = Side trunnion
- E = Extended tie rods
- J = Metric side mount
- K = Metric double side mount
- Q = Metric side trunnion
- M = Metric extended tie rods
- G = Metric rear clevis
- Z = Clevis mount with same pin to pin as SR Series
- X = Special (please specify)

**F = Rod End**

- M = Male, US std. thread
- A = Male, metric thread
- F = Female, US std. thread
- B = Female, metric thread
- W = Male, US std. thread 17-4 SS
- R = Male metric thread 17-4 SS
- V = Female, US std. thread 17-4 SS
- L = Female, metric thread 17-4 SS
- X = Special (please specify)

**GGG = Feedback Type (Also specify the Amplifier/Drive Model being used when ordering)**

- Standard Incremental Encoder – 2048 line (8192 cts) per rev. index pulse, Hall commutation, 5vdc
- Standard Resolver – Size 15, 1024 line (2048 cts) per rev. two pole resolver
- Motor files for use with select Emerson/CT, Rockwell /AB and Danaher/Kollmorgen Drives are available at [www.exlar.com](http://www.exlar.com)
- Custom Feedback:** Please consult application engineering:
- XX1 = Wiring and feedback device information must be provided and new feedback callout will be created

**Allen-Bradley/Rockwell:** (Actuators used with Kinetix and/or Sercos based control systems require a .cmf file from AB/Rockwell. Please contact your AB/Rockwell representative for support.)

- AB8 = Standard Incremental Encoder – MPL Circular (Speedtec) DIN connectors for 'M' option
- AB9 = Hiperface Stegmann SRM050 absolute encoder – 40 Frame Size. MPL Circular (Speedtec) DIN connectors for 'M' option – Plug & Play feedback option<sup>12</sup>
- ABB = Hiperface Stegmann SKM036 multi-turn absolute encoder. 20-30 Frame Size. MPL Circular (Speedtec) DIN connectors for 'M' option – Plug & Play feedback option<sup>12</sup>

**AMKASYN:**

- AK1 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – 40 Frame Size. DS motor wiring w/M23 euro connectors for 'M' option
- AK2 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – 20-30 Frame Size. DS motor wiring w/M23 euro connectors for 'M' option

**Advanced Motion Control:**

- AM1 = Standard Incremental Encoder
- AM2 = Encoder 1000 line, w/commutation, 5 VDC
- AM3 = Standard Resolver
- AM5 = Encoder 5000 line, w/commutation, 5 VDC

**API Controls:**

- AP1 = Standard Resolver
- AP2 = Standard Incremental Encoder

**Aerotech:**

- AR1 = Encoder 5000 line, w/commutation, 5 VDC
- AR2 = Standard Incremental Encoder

**ABB Robot:**

- BB1 = LTN Resolver

**Baldor:**

- BD2 = Std Resolver – BSM motor wiring w/M23 connectors for 'M' option
- BD3 = Std Incremental Encoder – BSM motor wiring w/M23 connectors for 'M' option

**Beckhoff:**

- BE2 = EnDat Heidenhain EQN1125/EQN1325 multi-turn absolute encoder – AM5XX motor wiring w/M23 euro connectors for 'M' option

**Baumuller:**

- BM2 = Standard Resolver

**B&R Automation:**

- BR1 = Standard Resolver
- BR2 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – 8LS/8LM motor wiring w/M23 euro connectors for 'M' option

**Comau Robot:**

- CM1 = Standard Resolver

**Copley Controls:**

- CO1 = Standard Incremental Encoder
- CO2 = Standard Resolver

**Control Techniques/Emerson:**

- CT1 = Hiperface Stegmann SRM050 multi-turn absolute encoder – 40 Frame Size. FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option
- CT3 = Hiperface Stegmann SKM036 multi-turn absolute encoder – 20-30 Frame Size. FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option
- CT4 = Standard Incremental Encoder – FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option
- CT5 = Standard Resolver – FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option
- CT7 = Encoder 5000 line, w/commutation, 5 VDC – FM/UM/EZ motor wiring w/M23 euro connectors for 'M' option

**Delta Tau Data Systems:**

- DT1 = Encoder 1000 line, w/commutation, 5 VDC
- DT2 = Standard Resolver

**Elmo Motion Control:**

- EL1 = Standard Resolver
- EL2 = Standard Incremental Encoder
- EL3 = EnDat Heidenhain EQN1125 multi-turn absolute encoder

**Emerson/Control Techniques:**

- EM2 = Std Incremental Encoder – NT motor wiring w/MS connectors for 'M' option
- EM5 = Encoder 5000 line, with commutation, 5 VDC – NT motor wiring w/MS connectors for 'M' option

**Elau:**

- EU1 = Hiperface Stegmann SRM050 multi-turn absolute encoder – 40 Frame Size. SH motor wiring w/MS connectors for 'M' option
- EU4 = Hiperface Stegmann SKM036 multi-turn absolute encoder – 20-30 Frame Size. SH motor wiring w/MS connectors for 'M' option

**Exlar:**

- EX4 = Standard Resolver

**Fanuc Pulsecoder:** Consult Exlar

**G&L Motion Control/Danaher Motion:**

- GL1 = Std Incremental Encoder – HSM motor wiring w/ MS connectors for 'M' option
- GL2 = Std Incremental Encoder – LSM-MSM motor wiring w/M23 euro connectors for 'M' option
- GL3 = Std Incremental Encoder – NSM motor wiring w/MS connectors for 'M' option

GL4 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – AKM motor wiring w/M23 euro connectors for 'M' option

**Infranor:**

IF1 = Standard Resolver

**Indramat/Bosch-Rexroth:**

IN6 = Std Resolver – MKD/MHD motor wiring w/M23 euro connectors for 'M' option

IN7 = Hiperface Stegmann SKM036 multi-turn absolute encoder – MSK motor wiring w/M23 euro connectors for 'M' option – plug & play option

**Jetter Technologies:**

JT1 = Standard Resolver – JH/JL motor wiring w/M23 euro connectors for 'M' option

**Kollmorgen/Danaher:**

KM4 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – AKM motor wiring w/M23 euro connectors for 'M' option

KM5 = Standard Resolver – AKM motor wiring w/M23 euro connectors for 'M' option

KM6 = Standard Incremental Encoder – AKM motor wiring w/M23 euro connectors for 'M' option

**Kuka Robot:**

KU1 = Tyco Size 21 Resolver

**Kawasaki Robot:**

KW1 = Kawasaki Special Encoder

**Lenze/AC Tech:**

LZ1 = Hiperface Stegmann SRM050 multi-turn absolute encoder – MCS motor wiring w/M23 euro connectors for 'M' option

LZ5 = Std Resolver – MCS motor wiring w/ M23 euro connectors for 'M' option

LZ6 = Std Incremental Encoder – MCS motor wiring w/ M23 euro connectors for 'M' option

**Matuschek:**

MC1 = LTN Resolver

**Metronix:**

MX1 = Standard Resolver

MX2 = Hiperface Stegmann SKM036 multi-turn absolute encoder

MX3 = EnDat Heidenhain EQN1125 multi-turn absolute encoder

**Mitsubishi:**

MT1 = Mitsubishi Absolute Encoder – HF-SP motor wiring with 'M' option

**Modicon:**

MD1 = Standard Resolver

**Momentum:**

MN1 = Hyperface Stegmann SRM050 multi-turn absolute encoder – MN motor wiring w/M23 connectors for 'M' option

MN2 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – MN motor wiring connectors for 'M' option

MN3 = Std incremental encoder – MN motor wiring w/M23 connectors for 'M' option

MN4 = Std resolver – MN motor wiring w/M23 connectors for 'M' option

**Moog:**

MG1 = Standard Resolver

**Motoman Robot:**

MM1 = Yaskawa Serial Encoder

**Nachi Robot:**

NC1 = Tamagawa Serial Encoder

**Ormec:**

OR1 = Standard Resolver

OR2 = Std Incremental Encoder – G series motor wiring w/MS connectors for 'M' option

**Parker Compumotor:**

PC6 = Std Incremental Encoder – SMH motor wiring w/M23 connectors for 'M' option – European only

PC7 = Std Resolver – SMH motor wiring w/M23 connectors for 'M' option – European only

PC8 = Std Incremental Encoder – MPP series motor wiring w/PS connectors for 'M' option – US Only

PC9 = Hiperface Stegmann SRM050 multi-turn absolute encoder – MPP motor wiring w/ PS connectors for 'M' option – US Only

PC0 = Std Resolver – MPP motor wiring w/PS connectors for 'M' option – US Only

**Pacific Scientific:**

PS2 = Standard Incremental Encoder

PS3 = Standard Resolver – PMA motor wiring w/M23 connectors for 'M' option

**Stober Drives:**

SB3 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – ED/EK motor wiring w/M23 euro connectors for 'M' option

**Siemens:**

SM2 = Standard Resolver – 1FK7 motor wiring w/M23 connectors for 'M' option

SM3 = EnDat Heidenhain EQN1325 multi-turn absolute encoder – 40 Frame Size. 1FK7 motor wiring w/M23 euro connectors for 'M' option

SM4 = EnDat Heidenhain EQN1125 multi-turn absolute encoder – 20-30 Frame Size. 1FK7 motor wiring w/M23 euro connectors for 'M' option

**SEW/Eurodrive:**

SW1 = Standard Resolver – CM motor wiring w/ M23 euro connectors for 'M' option

SW2 = Standard Incremental Encoder

SW3 = Hiperface Stegmann SRM050 multi-turn absolute encoder – CM motor wiring w/ M23 euro connectors for 'M' option

**Whedco:**

WD1 = Standard Resolver

**Yaskawa:**

YS2 = Yaskawa Absolute Encoder – SGMGH motor wiring 40/50/60 Exlar Frame Sizes

YS3 = Yaskawa Absolute Encoder – SGMGH motor wiring 20/30 Exlar Frame Sizes

**HHH = Motor Stator<sup>2</sup> – All 8 Pole**

118 = 1 stack	115	158 = 1 stack	400
218 = 2 stack	Vrms	258 = 2 stack	Vrms
138 = 1 stack	230	168 = 1 stack	460
238 = 2 stack	Vrms	268 = 2 stack	Vrms

**II = Motor Speed**

30 = 3000 rpm, GSM30, GSM40

50 = 5000 rpm, GSM20

01- 99 = Customer specified base speed

**XX .. XX = Travel and Housing Options (please list desired options)**

**Travel Options**

AR = External anti-rotate

HW = Side handwheel manual drive with limit switch<sup>10</sup>

PB = Protective bellows<sup>11</sup>

SR = Splined main rod

RB = Rear brake

RD = Rear manual drive<sup>9</sup>

SD = Hex side drive

PF = Preloaded follower<sup>4</sup>

L1/L2/L3 = External limit switch<sup>8</sup>

XT = Special travel options, high temperature bellows<sup>11</sup> or angular contact bearings

**Housing Options**

EN = Electroless nickel plating

XH = Special housing

P5 = IP65 sealing option<sup>5</sup>

HC = Type III hard coat anodized<sup>6</sup>

XL = Special lubrication, food grade or Mobilgrease 28, specify

XM = Special motor options

**Absolute Linear Feedback**

LT = ICT, including signal conditioner<sup>4,7,9</sup>

**##### = Part No. Designator for Specials**

Optional 5 digit assigned part number to designate unique model numbers for specials.

**Note:**

- Available as described in Feedback Types.
- Stator voltage and pole options allow for catalog rated performance at varying amplifier bus voltages and pole configuration requirements.
- 0.75 lead not available over 12" stroke
- The dynamic load rating of zero backlash, preloaded screws is 63% of the dynamic load rating of the standard non-preloaded screws. The calculated travel life of a preloaded screw will be 25% of the calculated travel life of the same size and lead of a non-preloaded screw. Preloaded follower is not available with absolute linear (LT) internal feedback option.
- Not available with splined main rod option.
- This housing option would typically be accompanied by the choice of the electroless nickel connectors if a connectorized unit were selected. This choice may also indicate the need for special material main rods or mounting.
- Linear feedback is not available in the GSM20 and not available in the GSM30, 14" and 18".
- Requires AR option
- Not available with absolute feedback.
- Not available on GSM20.
- Not available with extended tie rod mounting option.
- Not compatible with Kinetix 300 drives.